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### RADIAL VIBRATION OF MAGNETO-VISCO-ELASTIC CYLINDRICAL SHELL

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**Abstract:** This paper investigates the radial vibration of magneto visco-elastic shell. The material of the shell being aeolotropic and density  $\rho$  of the shell varies as  $\rho = \rho_0 r^n$ , where  $\rho_0$  is constant and n is any integer. Lastly, frequency equation have been derived.

Keywords and Phrases: Radial vibration, magneto visco-elastic shell, frequency equation

2000 AMS Subject Classification: 74J15, 74D05

### 1. Introduction

Recently, a great deal of activity has emerged in the study of interaction of elastic and electromagnetic fields due to their extensive applications in science and technology. Kaliski [1], Narain [3,4], Narain and Srivastava [5], Narain and Verma [6,7], Nowacki [8], Nowacki and Kaliski [9], Paria [10] and many other have investigated the problems concerning elastic and electromagnetic fields. Sequal to there, the present paper in an attempt to investigate radial vibration of megnetovisco-elastic shell. The material of the shell being aeolotropic and density of the shell to be varying as the integral power of radius vector in the form  $\rho = \rho_0 r^n$ where  $\rho_0$  is constant and n is any integer. Frequency equation in several cases have been derived.

#### 2. Fundamental Equations and Boundary Conditions

We consider aeolotropic visco-elastic prefectly conducting cylindrical shell of inner radius  $r_1$  and outer radius  $r_2$ , and assumed that the space outside the shell to be surrounded by vacuum. We also consider that the boundary of the shell is mechanically stressed free. Initially, there exists an axial magnetic field of intensity  $\vec{H}$  in the shell. The constituting relation for aeolotropic visco-elastic bodies in cylindrical co-ordinates  $(r, \theta, z)$  may be written as

$$\sigma_{rr} = \left(\lambda + \lambda' \frac{\partial}{\partial t} + \lambda'' \frac{\partial^2}{\partial t^2}\right) e_{rr}$$
  

$$\sigma_{\theta\theta} = \left(\lambda + \lambda' \frac{\partial}{\partial t} + \lambda'' \frac{\partial^2}{\partial t^2}\right) e_{\theta\theta}$$
  

$$\sigma_{zz} = \left(\lambda + \lambda' \frac{\partial}{\partial t} + \lambda'' \frac{\partial^2}{\partial t^2}\right) e_{zz}$$
(2.1)

where  $\sigma_{rr}$ ,  $\sigma_{\theta\theta}$ ,  $\sigma_{zz}$  and  $e_{rr}$ ,  $e_{\theta\theta}$ ,  $e_{zz}$  are the components of stress and strain respectively,  $\lambda$ ,  $\lambda'$ ,  $\lambda''$  are material constants. The equation of motion of magnetoelasticity for a perfect conductor with unit permeability as given by Kaliski [1] are

$$\frac{\partial \sigma_{rr}}{\partial r} + \frac{1}{r}(\sigma_{rr} - \sigma_{\theta\theta}) + \frac{1}{4\pi} \Big\{ rot.rot(\vec{u} \times \vec{H}) \Big\} \times \vec{H} = \rho \frac{\partial^2 u_r}{\partial t^2}$$
(2.2)

$$\vec{E} = -\frac{1}{c}\frac{\partial \vec{u}}{\partial t} \times \vec{H}, \qquad \vec{h} = rot.(\vec{u} \times \vec{H})$$
 (2.3)

where  $\vec{u}$  is the mechanical displacement vector.  $\vec{E}$  is the electric intensity vector and  $\vec{h}$  the perturbation in the magnetic intensity vector.

The electromagnetic field equations is vacuum are

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \vec{E}^* = 0; \qquad (2.4)$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \vec{h}^* = 0; \qquad (2.5)$$

$$rot.\vec{E}^* = -\frac{1}{c}\frac{\partial\vec{h}^*}{\partial t}; \qquad (2.6)$$

$$rot.\vec{h}^* = -\frac{1}{c}\frac{\partial \vec{E}^*}{\partial t}, \qquad (2.7)$$

where  $\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r}$ ;  $\vec{E}^*$ ,  $\vec{h}^*$  denote the value of  $\vec{E}$  and  $\vec{h}$  respectively in vacuum. The components of strain as gives in Love [2] are

$$e_{rr} = \frac{\partial u_r}{\partial r}, \quad e_{\theta\theta} = \frac{1}{r} \frac{\partial u_{\theta}}{\partial \theta} + \frac{u_r}{r}, \quad e_{zz} = \frac{\partial u_z}{\partial z}, \quad 2e_{\theta z} = \frac{1}{r} \frac{\partial u_z}{\partial \theta} + \frac{\partial u_{\theta}}{\partial z}$$
$$2e_{rz} = \frac{\partial u_r}{\partial z} + \frac{\partial u_z}{\partial r}, \quad 2e_{r\theta} = \frac{\partial u_{\theta}}{\partial r} - \frac{u_{\theta}}{r} + \frac{1}{r} \frac{\partial u_r}{\partial \theta}.$$

For radial vibration, we have

$$u_{\theta} = u_z = 0, \quad u_r = U(r)e^{iwt}$$
 (2.8)

The components of strain take the form

$$e_{rr} = \frac{\partial u}{\partial r} e^{iwt}, \quad e_{\theta\theta} = \frac{u}{r} e^{iwt}, \quad e_{zz} = 0$$
 (2.9)

Also,

$$e_{\theta z} = e_{rz} = e_{r\theta} = 0$$
  

$$h_{r}^{*} = h_{\theta}^{*} = 0, \quad h_{z}^{*} = h^{*} = V(r)e^{iwt}$$
  

$$H_{r} = H_{\theta} = 0, \quad H_{z} = H$$
  

$$E_{r}^{*} = E_{\theta}^{*} = 0, \quad E_{z}^{*} = We^{iwt}$$
  
(2.10)

where V and W are functions of r alone.

The equation (2.3) gives

$$E = -\frac{H_1}{c} \frac{\partial u}{\partial t} = -\frac{iw}{c} H_1 U e^{iwt}$$

$$h = -\frac{H_1}{r} \frac{\partial (ru)}{\partial r} = -H_1 \left(\frac{\partial U}{\partial r} + \frac{U}{r}\right) e^{iwt}.$$
(2.11)

From (2.5), (2.7) and (2.10) we get

$$\frac{\partial^2 U}{\partial r^2} + \frac{1}{r} \frac{\partial U}{\partial r} + \frac{w^2}{c^2} U = 0$$
(2.12)

$$W = \frac{ic}{w} \frac{\partial U}{\partial r}.$$
 (2.13)

The boundary conditions are given by

$$\begin{aligned}
\sigma_{rr} + T_{rr} &= T_{rr}^{*} & \text{ on } r = r_{1}; \\
\sigma_{rr} + T_{rr} &= T_{rr}^{*} & \text{ on } r = r_{2}; \\
\vec{E} &= \vec{E}^{*} & \text{ on } r = r_{1}; \\
\vec{E} &= \vec{E}^{*} & \text{ on } r = r_{2},
\end{aligned}$$
(2.14)

where  $T_{rr}$ ,  $T_{rr}^*$  are Maxwellian tensors in the shell and vacuum respectively and may be expressed as

$$T_{rr} = -\frac{H_1}{4\pi}h = \frac{H_1^2}{4\pi}\left(\frac{\partial U}{\partial r} + \frac{U}{r}\right)e^{iwt}$$
  

$$T_{rr}^* = -\frac{H_1}{4\pi}h^* = \frac{H_1}{4\pi}Ue^{iwt}.$$
(2.15)

Therefore, the stress equation (2.1) with the help of equations (2.8) and (2.9) takes the form

$$\sigma_{rr} = \left(\lambda + \lambda' \frac{\partial}{\partial t} + \lambda'' \frac{\partial^2}{\partial t^2}\right) \frac{\partial U}{\partial r} e^{iwt}$$
(2.16)

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$$\sigma_{\theta\theta} = \left(\lambda + \lambda' \frac{\partial}{\partial t} + \lambda'' \frac{\partial^2}{\partial t^2}\right) \frac{U}{r} e^{iwt}.$$
 (2.17)

In case of radial vibration

$$\frac{1}{4\pi} \left\{ rot.rot(\vec{u} \times \vec{H}) \right\} \times \vec{H} = \frac{H^2}{4\pi} \left\{ \frac{\partial^2 U}{\partial r^2} + \frac{1}{r} \frac{\partial U}{\partial r} - \frac{U}{r^2} \right\} e^{iwt}.$$
(2.18)

### 3. Method of Solution

Suppose that the material density  $\rho$  varies as

$$\rho = \rho_0 r^n \tag{3.1}$$

where  $\rho_0$  is constant and *n* is any integer, using equations (2.16), (2.17) and (2.18) the equation (2.2) gives

$$\frac{\partial^2 U}{\partial r^2} + \frac{1}{r} \frac{\partial U}{\partial r} - \frac{U}{r^2} + \frac{\rho_0 r^n w^2 U}{\left(K + \frac{H^2}{4\pi}\right)} = 0$$
(3.2)

where

$$K = \lambda + iw\lambda' - w^2\lambda'' \tag{3.3}$$

using the transformation,

$$x = \frac{2}{n+2} r^{(n+2)/2}$$
(3.4)

the equation (3.2), takes the form

$$\frac{\partial^2 U}{\partial x^2} + \frac{1}{x} \frac{\partial U}{\partial x} + \left\{ \mu^2 - \frac{\alpha^2}{x^2} \right\} U = 0$$
(3.5)

where

$$\mu^{2} = \frac{\rho_{0}w^{2}}{\left(K + \frac{H^{2}}{4\pi}\right)}, \quad \alpha^{2} = \frac{2}{n+2}.$$
(3.6)

The solution of the equation (3.5) is given by

$$U = AJ_{\alpha}(\mu x) + BY_{\alpha}(\mu x) \tag{3.7}$$

where  $J_{\alpha}$  and  $Y_{\alpha}$  are the Bessel's functions of first and second kind of order  $\alpha$ , A and B are constants.

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Using equations (2.9) and (3.7), the equations (2.1) and (2.15) take the form

$$\sigma_{rr} = (\lambda + \lambda' i w - w^2 \lambda'') \left\{ A r^{n/2} J_{\alpha - 1} \left( \frac{2\mu r^{(n+2)/2}}{n+2} \right) + B r^{n/2} Y_{\alpha - 1} \left( \frac{2\mu r^{(n+2)/2}}{n+2} \right) \right\} e^{iwt}$$
(3.8)

and

$$T_{rr} = \frac{H^2}{4\pi} \left[ \begin{array}{c} A \left\{ \mu r^{n/2} J_{\alpha-1} \left( \frac{2\mu}{n+2} r^{(n+2)/2} \right) + \frac{1}{r} J_{\alpha} \left( \frac{2\mu}{n+2} r^{(n+2)/2} \right) \right\} \\ + B \left\{ \mu r^{n/2} Y_{\alpha-1} \left( \frac{2\mu}{n+2} r^{(n+2)/2} \right) + \frac{1}{r} Y_{\alpha} \left( \frac{2\mu}{n+2} r^{(n+2)/2} \right) \right\} \end{array} \right] e^{iwt}.$$

$$(3.9)$$

Again, the solution of the equation (2.12) is given by

$$U = CJ_0\left(\frac{wr}{c}\right) + DY_0\left(\frac{wr}{c}\right), \qquad (3.10)$$

where C and D are constants and  $J_0$ ,  $Y_0$  are Bessel's functions of order zero. Hence, the Maxwellian tensor  $T^*_{rr}$  in vacuum is given by

$$T_{rr}^* = \frac{H}{4\pi} U e^{iwt} = \frac{H}{4\pi} \left\{ C J_0\left(\frac{wr}{c}\right) + D Y_0\left(\frac{wr}{c}\right) \right\} e^{iwt}$$
(3.11)

thus,

$$T_{rr}^{*} = \begin{cases} \frac{H}{4\pi} C J_{0}\left(\frac{wr}{c}\right) & \text{on } r \geq r_{2} \\ \frac{H}{4\pi} D Y_{0}\left(\frac{wr}{c}\right) & \text{on } r \leq r_{2} \end{cases}$$

$$(3.12)$$

Using equation (3.8), the equation (2.11) gives

$$E = -\frac{iw}{c} HUe^{iwt} = -\frac{iwH}{c} \left\{ AJ_{\alpha} \left( \frac{2\mu}{n+2} r^{(n+2)/2} \right) + BY_{\alpha} \left( \frac{2\mu}{n+2} r^{(n+2)/2} \right) \right\} e^{iwt}$$
(3.13)

Using equation (3.7) in equation (2.13) we get

$$E^* = we^{iwt} = \frac{ic}{w} \frac{\partial U}{\partial r} e^{iwt} = -i \left\{ CJ_1\left(\frac{wr}{c}\right) + DY_1\left(\frac{wr}{c}\right) \right\} e^{iwt}.$$
 (3.14)

Hence,

$$E^* = \left\{ \begin{array}{cc} -iCJ_1\left(\frac{wr}{c}\right) & \text{on } r \ge r_2 \\ \\ -iDY_1\left(\frac{wr}{c}\right) & \text{on } r \le r_2 \end{array} \right\}.$$
(3.15)

Using equations (3.8), (3.9) and (3.2), the equation (2.14) gives

$$AX_{11} + BX_{12} + DX_{14} = 0 (3.16)$$

$$AX_{21} + BX_{22} + CX_{23} = 0. (3.17)$$

Using the equation (3.13) and (3.5), the equation (2.14) gives

$$AX_{31} + BX_{32} + DX_{34} = 0 (3.18)$$

$$AX_{41} + BX_{42} + CX_{43} = 0. (3.19)$$

where

$$\begin{split} X_{11} &= L_1 \left\{ \mu r_1^{n/2} J_{\alpha-1} \left( \frac{2\mu}{n+2} r_1^{(n+2)/2} \right) \right\}, \\ X_{12} &= L_1 \left\{ \mu r_1^{n/2} Y_{\alpha-1} \left( \frac{2\mu}{n+2} r_1^{(n+2)/2} \right) \right\}, \\ X_{14} &= \frac{H}{4\pi} Y_0 \left( \frac{\omega r_1}{c} \right), \\ X_{21} &= \mu r_2^{n/2} J_{\alpha-1} \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right) + \frac{1}{r_2} J_\alpha \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right), \\ X_{22} &= \mu r_2^{n/2} Y_{\alpha-1} \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right) + \frac{1}{r_2} Y_\alpha \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right), \\ X_{23} &= -\frac{H}{4\pi} J_0 \left( \frac{\omega r_1}{c} \right), \\ X_{31} &= -\frac{\omega H}{c} J_\alpha \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right), \\ X_{32} &= -\frac{\omega H}{c} Y_\alpha \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right), \\ X_{34} &= Y_1 \left( \frac{\omega r_1}{c} \right), \\ X_{41} &= \frac{\omega H}{c} J_\alpha \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right), \\ X_{42} &= \frac{\omega H}{c} Y_\alpha \left( \frac{2\mu}{n+2} r_2^{(n+2)/2} \right), \\ X_{43} &= J_1 \left( \frac{\omega r_2}{c} \right). \end{split}$$

Eliminating A, B, C, D from equations (3.16),(3.17),(3.18) and (3.19) we get

$$\begin{vmatrix} X_{11} & X_{12} & 0 & X_{14} \\ X_{21} & X_{22} & X_{23} & 0 \\ X_{31} & X_{32} & 0 & X_{34} \\ X_{41} & X_{42} & X_{43} & 0 \end{vmatrix} = 0$$

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On solving the determinants, we get

$$\frac{X_{14} X_{32} + X_{34} X_{12}}{X_{23} X_{43} - X_{23} X_{42}} = \frac{X_{11} X_{34} + X_{14} X_{31}}{X_{43} X_{21} - X_{41} X_{42}}$$
$$\frac{P}{Q} = \frac{R}{S}$$
(3.20)

where

$$\begin{split} P &:= \frac{H^2}{4\pi} \frac{\omega}{c} Y_0\left(\frac{\omega r_1}{c}\right) Y_\alpha\left(\frac{2\mu}{n+2} r_1^{(n+2)/2}\right) + Y_1\left(\frac{\omega r_1}{c}\right) Y_{\alpha-1}\left(\frac{2\mu}{n+2} r_1^{(n+2)/2}\right) \\ Q &:= -\frac{wH^2}{4\pi c} J_0\left(\frac{\omega r_2}{c}\right) Y_\alpha\left(\frac{2\mu}{n+2} r_2^{(n+2)/2}\right) \\ &+ J_1\left(\frac{\omega r_2}{c}\right) \left\{ \mu r_2^{n/2} Y_{\alpha-1}\left(\frac{2\mu}{n+2} r_2^{(n+2)/2}\right) + \frac{1}{r_2} Y_\alpha\left(\frac{2\mu}{n+2} r_2^{(n+2)/2}\right) \right\} \\ R &:= \frac{H^2}{4\pi} \frac{\omega}{c} Y_0\left(\frac{\omega r_1}{c}\right) J_\alpha\left(\frac{2\mu}{n+2} r_1^{(n+2)/2}\right) + Y_1\left(\frac{\omega r_1}{c}\right) J_{\alpha-1}\left(\frac{2\mu}{n+2} r_1^{(n+2)/2}\right) \\ S &:= -\frac{wH^2}{4\pi c} J_0\left(\frac{\omega r_2}{c}\right) J_\alpha\left(\frac{2\mu}{n+2} r_2^{(n+2)/2}\right) \\ &+ J_1\left(\frac{\omega r_2}{c}\right) \left\{ \mu r_2^{n/2} J_{\alpha-1}\left(\frac{2\mu}{n+2} r_2^{(n+2)/2}\right) + \frac{1}{r_2} J_\alpha\left(\frac{2\mu}{n+2} r_2^{(n+2)/2}\right) \right\}. \end{split}$$

If x is small, we use the following relations

$$Y_0(x) = O(\log x) = K \log x$$
  

$$Y_n(x) = O\left(\frac{1}{x^n}\right) = \frac{K}{x^n}, \text{ where } K \text{ is constant};$$
  

$$J_n(x) = \frac{x^n}{2^n \sqrt{n+1}}.$$
(3.21)

After simplification equation (3.20) together with equation (3.21) we get

$$\frac{\rho_0 H^2}{2\pi c^2 \left(K + \frac{H^2}{4\pi}\right)^{1/2} \alpha} \left(\frac{r_2}{r_1}\right)^{\sqrt{2(n+2)}} w^4 + \left\{-\frac{H^4}{8\pi^2 c^2 \alpha} \left(\frac{r_2}{r_1}\right)^{\sqrt{2(n+2)}} + \frac{H^2}{4\pi c^2 \alpha} \left(\frac{r_2}{r_1}\right)$$

、

$$+\frac{2\rho_{0}r_{1}^{n/2}}{(n+2)\left(K+\frac{H^{2}}{4\pi}\right)^{1/2}}\left(\frac{r_{2}}{r_{1}}\right)^{\sqrt{2(n+2)}}+\frac{H^{2}(n+2)}{4\pi c^{2}\rho_{0}r_{2}^{n/2}}\left(K+\frac{H^{2}}{4\pi}\right)^{1/2}\right\}w^{2}$$
$$+\left\{\left(\frac{r_{2}}{r_{1}}\right)^{\frac{n+2}{2}+1}-\left[\left(\frac{r_{1}}{r_{2}}\right)^{n/2}\left(\frac{r_{2}}{r_{1}}\right)\right]^{\sqrt{2(n+2)}}\right\}$$
$$+\frac{H^{2}(n+2)\left(K+\frac{H^{2}}{4\pi}\right)^{1/2}}{\partial \pi \rho_{0}r_{1}^{\frac{n+2}{2}+1}}+\frac{(n+2)\left(K+\frac{H^{2}}{4\pi}\right)^{2}}{\partial \rho_{0}r_{1}^{\frac{(n+2)}{2}+1}}=0.$$
(3.22)

If there were no magnetic field, i.e., H = 0 and  $\lambda' = \lambda'' = 0$  then the frequency equation at for  $n = 0 \Rightarrow \alpha = 1$  for aeolotgropic cylindrical shell as

$$w^2 = \frac{\lambda^2}{r_2^2 \rho_0^2}.$$
 (3.23)

The presence of  $r_2$  in the dimensional of frequency equation (3.23) indicates that the frequency decreases when  $r_2$  increases. It also indicates that the frequency does not depend upon the inner radius of the shell.

The following table indicates the frequency of different material:

S. No.	Material	$ ho_0$	$\lambda$	$r_2$	w	$\omega = w \times 10^{11}$
1.	Copper	8.9	$8.5 imes10^{11}$	1	$1.06 imes10^{11}$	1.06
				2	$0.53 imes10^{11}$	0.53
				3	$0.35 imes10^{11}$	0.35
				4	$0.27 imes10^{11}$	0.27
2.	Steel	7.8	$11.2  imes 10^{11}$	1	$1.43  imes 10^{11}$	1.43
				2	$0.73 imes10^{11}$	0.73
				3	$0.47 imes10^{11}$	0.47
				4	$0.36 imes10^{11}$	0.36
3.	Aluminium	2.7	$5.6 imes10^{11}$	1	$2.07 imes10^{11}$	2.07
				2	$1.03 imes10^{11}$	1.03
				3	$0.69 imes10^{11}$	0.69
				4	$0.51 imes10^{11}$	0.51
4.	Glass	2.5	$2.8 imes10^{11}$	1	$1.12  imes 10^{11}$	1.12
				2	$0.56 imes10^{11}$	0.56
				3	$0.28 imes10^{11}$	0.28
				4	$0.14 imes10^{11}$	0.14

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