South East Asian J. Math. & Math. Sc. Vol.2 No.1(2003), pp.61-65

ON M-PROJECTIVELY RECURRENT SASAKIAN MANIFOLDS

A. A. Shaikh and Sudipta Biswas

Department of Mathematics University of North Bengal, P.O.-NBU-734430, Darjeeling, India Email : aask2003@yahoo.co.in

(Received: June 30, 2003; Submitted by U.C. De)

Abstract: The object of this paper is to study M-projectively recurrent Sasakian manifolds.

Keywords and Phrases : Sasakian manifolds, *M*-projective curvature tensor, *M*-projectively recurrent manifold

A.M. Subject classification : 53C25

1. Introduction

Let $M^{2m+1}(\varphi, \xi, \eta, g)$ be a contact metric manifold with contact from η , the associated vector field ξ , (1,1)-tensor field φ and the associated Riemannian metric g. If ξ is a Killing vector field, then M^{2m+1} is called a K-contact Riemannian manifold [1,3]. A K-contact Riemannian manifold is called Sasakian [1] if and only if

$$(\nabla_X \varphi)(Y) = g(X, Y)\xi - \eta(Y)X \tag{1.1}$$

holds for all vector fields X, Y, where ∇ denotes the operator of covariant differentiation with respect to g. A Sasakian manifold is K-contact but not conversely. However, a 3-dimensional K-contact manifold is Sasakian.

Recently, R. H. Ojha [2] studied M-projectively flat Sasakian manifold and proved that an M-projectively recurrent Sasakian manifold is M-projectively flat if and only if it is an Einstein manifold. In the present paper we study Mprojectively recurrent Sasakian manifolds and it is proved that such a manifold is always an Einstein manifold and hence M-projectively flat.

2. Preliminaries

If R, S, r denote respectively the curvature tensor of type (1,3), the Ricci tensor of type (0,2) and the scalar curvature of a Sasakian manifold M^{2m+1} , then the following relations hold [1,3,4]:

a)
$$\varphi \xi = 0$$
, b) $\eta(\xi) = 1$, c) $g(X,\xi) = \eta(X)$, (2.1)

PDF Created with deskPDF PDF Writer - Trial :: http://www.docudesk.com

A. A. Shaikh and Sudipta Biswas

a)
$$\varphi^2 X = -X + \eta(X)\xi$$
, $g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y)$, (2.2)

a)
$$(\nabla_X \varphi)(Y) = R(\xi, X)Y$$
, b) $\nabla_X \xi = -\varphi X$, (2.3)

$$\eta(R(X,Y)Z) = g(Y,Z)\eta(X) - g(X,Z)\eta(Y),$$
(2.4)

$$S(X,\xi) = 2m\eta(X) \tag{2.5}$$

for any vector fields X, Y, Z.

The above results will be used in the next section.

3. M-Projectively Recurrent Sasakian Manifolds

This section deals with a Sasakian manifold which is M-projectively recurrent. A Sasakian manifold is said to be M-projectively recurrent if it satisfies

$$(\nabla_W M)(X, Y)Z = A(W)M(X, Y)Z, \qquad (3.1)$$

where A is a non-zero 1-form and the M-projective curvature tensor M in a Sasakian manifold is given by

$$M(X,Y)Z = R(X,Y)Z - \frac{1}{4m}[S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY],$$
(3.2)

Q is the Ricci-operator i.e., g(QX, Y) = S(X, Y).

We now define a function f on the manifold M^{2m+1} by $f^2 = g(M, M)$, where the Riemannian metric g is extended to the inner product between the tensor fields in the standard fashion. Then since $\nabla M = A \otimes M$, we get

$$\begin{aligned} f(Yf) &= f^2 A(Y). \text{ From this it follows that} \\ Yf &= f A(Y) \text{ (because } f \neq 0). \end{aligned}$$
 (3.3)

From (3.3) we obtain

$$X(Yf) = \frac{1}{f}(Xf)(Yf) + (XA(Y))f.$$

Hence

$$X(Yf) - Y(Xf) = \{XA(Y) - YA(X)\}f.$$

Therefore we get $(\nabla_X \nabla_Y - \nabla_Y \nabla_X - \nabla_{[X,Y]})f = \{XA(Y) - YA(X) - A([X,Y])\}f.$

Since the left hand side of the above equation is identically zero and $f\neq 0$ on M^{2m+1} by our assumption, we obtain

$$dA(X,Y) = 0. (3.4)$$

PDF Created with deskPDF PDF Writer - Trial :: http://www.docudesk.com

62

This means that the 1-form A is closed. Now from (3.1) we get

$$(\nabla_X \nabla_Y M)(U, V)W = \{XA(Y) + A(X)A(Y)\}M(U, V)W.$$

Hence from (3.4) we have

$$(R(X,Y)M)(U,V)W = [2dA(X,Y)]M(U,V)W = 0$$

Therefore for a M-projectively recurrent manifolds, we have

$$R(X,Y)M = 0, (3.5)$$

where R(X, Y) is considered as a derivation of the tensor algebra at each point of the manifold for tangent vectors X, Y.

By virtue of (2.1), (2.4) and (2.5), it follows from (3.2) that

$$\eta(M(X,Y)Z) = \frac{1}{4m} [S(X,Z)\eta(Y) - S(Y,Z)\eta(X) + 2m\{g(Y,Z)\eta(X) - g(X,Z)\eta(Y)\}].$$
(3.6)

Replacing X by ξ in (3.6) and using (2.5) we get

$$\eta(M(\xi, Y)Z) = \frac{1}{4m} [2mg(Y, Z) - S(Y, Z)].$$
(3.7)

Again from (3.6), it follows that

$$\eta(M(X,Y)\xi) = 0.$$
(3.8)

By definition from (3.5) we have

$$R(X,Y)M(U,V)W - M(R(X,Y)U,V)W - M(U,R(X,Y)V)W$$
$$-M(U,V)R(X,Y)W = 0.$$

This gives us

$$g(R(\xi, Y)M(U, V)W, \xi) - g(M(R(\xi, Y)U, V)W, \xi) - g(M(U, R(\xi, Y)V)W, \xi) - g(M(U, V)R(\xi, Y)W, \xi) = 0.$$
 (3.9)

In view of (2.3) (a) and (1), we obtain from (3.9)

$$M(U, V, W, Y) - \eta(Y)\eta(M(U, V)W) + \eta(V)\eta(M(U, V)W)$$

PDF Created with deskPDF PDF Writer - Trial :: http://www.docudesk.com

$$\eta(U)\eta(M(Y,V)W) + \eta(W)\eta(M(U,V)Y) - g(Y,U)\eta(M(\xi,V)W) -g(Y,V)\eta(MU,\xi)W = 0,$$
(3.10)

where (3.8) have been used, and M(U, V, W, Y) = g(M(U, V)W, Y).

Let $\{e_i\}$, $i = 1.2, \dots, 2m + 1$ be an orthogonal basis of the tangent space at any point of the manifold. Then putting $Y = U = e_i$ in (3.10) and taking summation for $1 \le i \le 2m + 1$, we get by virtue of (3.2), (3.6) and (3.7) that

$$S(V,W) = \alpha g(V,W) + \beta \eta(V)\eta(W) \text{ for all } V,W, \qquad (3.11)$$

where

$$\alpha = \frac{4m^2 + r}{4m + 1}$$
 and $\beta = \frac{4m^2 + 2m - r}{4m + 1}$

It follows from (3.11) that

$$r = 2m(2m+1). (3.12)$$

Using (3.12) in (3.11), we have

$$S(V,W) = 2mg(V,W) \text{ for all } V,W.$$
(3.13)

From (3.13) we can state the following:

Theorem 1. An *M*-projectively recurrent Sasakian manifold $M^{2m+1}(\varphi, \xi, \eta, g)$ (m > 1) is an Einstein manifold.

In view of (3.13), we obtain from (3.6) that

$$\eta(M(X,Y)Z) = 0 \text{ for all } X, Y, Z, \qquad (3.14)$$

which implies that

$$\eta(M(\xi, Y)Z) = 0. (3.15)$$

By virtue of (3.14) and (3.15), we get from (3.10) that

$$M(U, V, W, Y) = 0$$
 for all U, V, W, Y .

Hence we can state the follows:

Theorem 2. An *M*-projectively recurrent Sasakian manifold $M^{2m+1}(\varphi, \xi, \eta, g)$ (m > 1) is *M*-projectively flat.

PDF Created with deskPDF PDF Writer - Trial :: http://www.docudesk.com

64

For an *M*-projectively symmetric Riemannian manifold, we have $\nabla M = 0$ and hence the relation R(X, Y)M = 0 holds. Thus we have the following:

Corollary. An *M*-projectively symmetric Sasakian manifold $M^{2m+1}(\varphi, \xi, \eta, g)$ (m > 1) is *M*-projectively flat.

References

- Blair, D.E., Contact Manifolds in Riemannian Geometry, Lecture Notes in Mathematics 509, Springer Verlag, 1976.
- [2] Ojha, R.H., M-projectively flat Sasakian manifolds, Indian J. Pure Appl. Math. 17(4) (1986), 481-484.
- [3] Sasaki, S., Lecture Notes on Almost Contact Manifolds, Part I, Tohoku Univ. Tohoku, 1965.
- [4] Sasaki, S., Lecture Notes on Almost Contact Manifolds, Part II, Tohoku Univ. Tohoku, 1967.